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A. Fernández Valles

Department of Mathematics, University of Cádiz, Polígono río san Pedro s/n, 11510 Puerto Real, Spain

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#### Abstract

Let  $T = (T_1, ..., T_N)$  be a system of N commuting contractions defined on a infinite dimensional separable Hilbert space H. In this article, we will prove that if  $(1, ..., 1) \in \sigma_{He}(T) \cap \mathbb{T}^N$ , where  $\sigma_{He}(T)$ denotes the essential Harte spectrum of T and  $\mathbb{T}^N$  the unit politorus, respectively, then there exists a nontrivial cone C invariant for each contraction  $T_j$ ;  $j \in \{1, ..., N\}$ . This result complements recent results of Tsatsomeros and co-workers [Roderick Edwards, Judith J. McDonald, Michael J. Tsatsomeros, On matrices with common invariant cones with applications in neural and gene networks, Linear Algebra Appl. 398 (2005) 37–67; Michael Tsatsomeros, A criterion for the existence of common invariant subspaces of matrices, Linear Algebra Appl. 322 (1–3) (2001) 51–59]. © 2008 Published by Elsevier Inc.

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## 1. Introduction

Let  $T = (T_1, ..., T_N)$  be a *N*-tuple of commuting contractions defined on a Hilbert space *H*. We say that  $C \subset H$  is a cone of *H* if  $rC + sC \subset C$  for each  $r, s \ge 0$ . We say that *T* has a non-trivial invariant closed cone if there exists a closed cone  $C \subset H, C \ne H, \{0\}$  such that  $T_j(C) \subset C$  for each  $j \in \{1, ..., N\}$ .

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Similary we say that  $T = (T_1, ..., T_N)$  has a non-trivial invariant closed subspace if there exists  $F \subset H$ ,  $F \neq H$ , {0} closed subspace such that  $T_j(F) \subset F$  for each  $j \in \{1, ..., N\}$ .

If H is finite dimensional, the existence of common invariant cones and subspaces have been studied previously in [1,6]. This problem is very interesting for its applications to neural and gene networks.

From a theoretical point of view, we study the existence of common invariant cones for commuting contractions on the infinite dimensional setting. The problem turns really complicated when H is infinite dimensional. In fact, it is not even known the existence of a non-trivial closed invariant subspace or cone for a single operator defined on a separable Hilbert space. This is know as "The invariant subspace problem".

Let *T* be a bounded linear operator defined on a separable Banach space *X*. Let us say that *T* is cyclic if there exists  $x \in X$  such that

Linear Span{ $T^n x: n \in \mathbb{N}$ }

is dense in X. In this case x is called a cyclic vector for T. With this new terminology in hand, an operator T has a non-trivial invariant closed subspace if and only if T has a non-cyclic vector x.

On the other hand we say that *T* is supercyclic if there exists  $x \in X$  such that  $\{\lambda T^n x; \lambda \in \mathbb{C}, n \in \mathbb{N}\}$  is dense in *X*. In this case *x* is called a supercyclic vector for *T*. The existence of a non-supercyclic vector is in general a weaker condition than the existence of a invariant closed cone. For *N*-tuple of operators the existence of a non-trivial supercyclic vector and the existence of a invariant closed cone are not related. In [7] it was proved that under some hypothesis about the Harte spectrum of  $T = (T_1, \ldots, T_N), T_1, \ldots, T_N$  have a common non-supercyclic vector. For supercyclic operators and related questions we refer to the survey by Montes–Salas (see [3]).

The next section is devoted to prove our main result (Theorem 2.2). From our main result we being able to give a spectral sufficient condition which guarantees the existence of a common invariant closed cone for  $T_1, \ldots, T_N$  and complements the results by Tsatsomeros an co-workers (see [1,6]).

### 2. Main result

Let T be a contraction defined on a Hilbert space H. Let us consider the subspaces

$$M_1 = \{x \in H : T^n x \to 0\}$$

and

$$M_2 = \{ x \in H : (T^*)^n x \to 0 \}.$$

 $M_1$  and  $M_2$  are invariant closed subspaces for T and  $T^*$ , respectively. To find a non-trivial invariant closed subspace is sufficient to consider the cases  $M_1 = \{0\}$ , H and  $M_2 = \{0\}$ , H. Depending of the posibles combinations of  $M_1$  and  $M_2$ , the classes  $C_{00}$ ,  $C_{10}$ ,  $C_{01}$ ,  $C_{11}$  are defined. For example  $T \in C_{11}$  if  $M_1 = M_2 = H$ . Concretely in this case a result of Nagy–Foias guarantee the existence of a hyperinvariant closed subspace for T (see [5]).

In the case of an *N*-tuple  $T = (T_1, ..., T_N)$ , after the same reduction we have the cases  $T_j \in C_0$  or  $T_j \in C_0$ . We will guarantee the existence of a non-trivial invariant closed cone for the cases  $T_j \in C_0$ ,  $j \in \{1, ..., N\}$  or  $T_j \in C_0$ ,  $j \in \{1, ..., N\}$ , and under some spectral sufficient conditions.

Now we will see our main result. We will need the following technical lemma whose proof can be found in [4].

**Lemma 2.1.** There exists a sequence of positive numbers  $(c_i)$ ,  $i \in \mathbb{N}$  such that  $\sum_{i=1}^{\infty} c_i^2 = 1$  and  $\sum_{i=k+1}^{\infty} c_i^2 > 3c_k$  for all  $k \ge 1$ .

**Theorem 2.2.** Let  $T = (T_1, \ldots, T_N)$  be a N-tuple of commuting contractions such that  $(1, \ldots, 1) \in$  $\sigma_{He}(T) \cap \mathbb{T}^N$  and  $T_i \in C_0$  for each  $j \in \{1, \dots, N\}$ . If  $\{\alpha_n\} \subset [0, 1]$  is a sequence of real positive numbers converging to zero, then there exists  $x_0 \in H \setminus \{0\}$  such that for all multi-index n = $(n_1,\ldots,n_N)$  with  $n_j \ge 1$  for each  $j \in \{1,\ldots,N\}$ 

$$\operatorname{Re}\langle T_1^{n_1}\ldots T_N^{n_N}x_0,x_0\rangle \geq \alpha_{j(n)}$$

where j(n) is defined by  $j(n) = \max\{n_1, \dots, n_N\}$ .

**Proof.** Since  $T_1, \ldots, T_N$  are contractions, the point  $(1, \ldots, 1)$  is a boundary point, that is,  $(1, \ldots, 1) \in \partial \sigma_{He}(T)$  and therefore,  $(1, \ldots, 1) \in \sigma_{\pi e}(T)$ , here  $\sigma_{\pi e}(T)$  denotes the upper semi-Fredholm spectrum. Therefore, for all  $\varepsilon > 0$  and  $M \subset H$  of finite codimension, there exists  $v \in M$ of norm 1 such that

 $||T_i v - v|| < \varepsilon; \quad j \in \{1, \dots, N\}.$ 

We can suppose without loss of generality that the sequence  $(\alpha_n)$  is decreasing, in other case we will replace it for the sequence (sup{ $\alpha_i$ :  $j \ge n$ }). Let  $(c_n)$  be another real numbers sequence satisfying the conditions of Lemma 2.3. Let  $(\delta_n)$  be a sequence of real numbers satisfying

$$\delta_i < \frac{1-\alpha_1}{2^i}$$

and

$$\delta_i < \min\left\{\frac{c_k}{1-2^{i-k+1}}k \in \{1,\ldots,i+1\}\right\}.$$

Since  $\alpha_i \to 0$ , then there exists  $m_0$  such that  $\alpha_{m_0} < \sum_{i=2}^{\infty} c_i^2 - 3c_i$ . We will construct by induction two sequences  $(m_k)_{k=1}^{\infty} \subset \mathbb{N}$  and  $(x_i)_{i=1}^{\infty} \subset H$  from the following form.

Let us suppose that  $k \in \mathbb{N}$ , and that  $x_i \in H$  and  $m_i \in \mathbb{N}$  have been already constructed for i < k. We take  $M = \{v \in H : v \perp T_1^{n_1} \dots T_N^{n_N} x_i \text{ for } 0 \leq n_j \leq m_{k-1} \text{ and } i < k\}$ . since M is of finite codimension, there exists  $x_k$  of norm 1 such that

$$x_k \perp T_1^{n_1} \ldots T_N^{n_N} x_i$$

for  $0 \leq n_i \leq m_{k-1}$  and i < k and such that

$$\|T_1^{n_1}\ldots T_N^{n_N}x_k-x_k\|\leqslant \delta_k$$

By hypothesis  $T_i \in C_0$ . Let us consider  $m_k > m_{k-1}$  large enough such that

$$||T_{j}^{n}x_{i}|| < \delta_{k}, \quad j \in \{1, \dots, N\}$$
 (1)

for all  $n \ge m_k$  and all  $j \in \{1, \ldots, N\}$ , and

$$\alpha_{m_k} < \sum_{i=k+2}^{\infty} c_i^2 - 3c_{k+1}$$

However, since  $T_1, \ldots, T_N$  are contractions, we deduce from (1) that

$$||T_1^{s_1}\dots T_N^{s_N}x_i|| \leq \delta_k \quad \text{for all } i \leq k$$

and whenever  $\max\{s_1, \ldots, s_N\} \ge m_k$ .

Let us suppose that the sequences  $(m_k)$  and  $(x_k)$  have been constructed. Let us consider the vector  $x_0 = \sum_{i=1}^{\infty} c_i x_i$ . Since the sequence  $(x_i)$  is orthonormal  $||x_0|| = 1$ .

Given  $n = (n_1, \ldots, n_N)$  a multi-index such that  $j(n) = \max\{n_1, \ldots, n_k\} \leq m_0$ , then we have

$$\operatorname{Re}\langle T_{1}^{n_{1}} \dots, T_{N}^{n_{N}} x_{0}, x_{0} \rangle = \operatorname{Re} \sum_{i=1}^{\infty} c_{i} \langle T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i}, x_{0} \rangle$$

$$= \operatorname{Re} \sum_{i=1}^{\infty} c_{i} \left( \langle x_{i}, x_{0} \rangle - \left\langle \sum_{i=1}^{\infty} x_{i} - T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i}, x_{0} \right\rangle \right)$$

$$\geqslant \sum_{i=1}^{\infty} c_{i}^{2} - \sum_{i=1}^{\infty} c_{i} \| x_{i} - T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i} \|$$

$$\geqslant 1 - \sum_{i=1}^{\infty} c_{i} \delta_{i} > 1 - \sum_{i=1}^{\infty} \frac{1 - \alpha_{1}}{2^{i}} \geqslant \alpha_{j(n)}.$$
(2)

We use the inequality  $||T_1^{n_1} \dots T_N^{n_N} x_k - x_k|| \leq \delta_k$  in the third line of (2), and the inequality  $\delta_i < \frac{1-\alpha_1}{2i}$  in the fourth line.

Now let us suppose that  $m_{k-1} < j(n) \le m_k$  for  $k \ge 1$ , where  $j(n) = \max\{n_1, \ldots, n_N\}$  and  $n = (n_1, \ldots, n_N)$ :

$$\operatorname{Re}\langle T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{0}, x_{0} \rangle = \operatorname{Re} \sum_{i=1}^{k-1} c_{i} \langle T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i}, x_{0} \rangle$$

$$+ \operatorname{Re} c_{k} \langle T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{k}, x_{0} \rangle + \sum_{i=k+1}^{\infty} \operatorname{Re} c_{i} \langle T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i}, x_{0} \rangle$$

$$\geqslant \sum_{i=1}^{k-1} c_{i} \delta_{k-1} - c_{k} + \sum_{i=k+1}^{\infty} c_{i} ||x_{i} - T_{1}^{n_{1}} \dots T_{N}^{n_{N}} x_{i} ||$$

$$\geqslant -(k-1)\delta_{k-1} - c_{k} + \sum_{i=k+1}^{\infty} \delta_{i}$$

$$\geqslant \sum_{i=k+1}^{\infty} c_{i}^{2} - 3c_{k} \geqslant \alpha_{m_{k-1}} \geqslant \alpha_{j(n)}.$$
(3)

We use the inequality  $\alpha_{m_k} < \sum_{i=k+2}^{\infty} c_i^2 - 3c_{k+1}$  in the last line of (3). Therefore, the proof is complete.  $\Box$ 

Using Theorem 2.2, we can obtain the following consequence which complement the results by Tsatsomeros and co-workers [1,6] in the finite dimensional setting.

**Corollary 2.3.** Let  $T = (T_1, ..., T_N)$  be a *N*-tuple of commuting contractions, and let us suppose that  $(1, ..., 1) \in \sigma_{He}(T) \cap \mathbb{T}^N$  and  $T_j \in C_0$  for each  $j \in \{1, ..., N\}$ . Then there exists a closed cone *C* such that  $T_j(C) \subset C$  for each  $j \in \{1, ..., N\}$ .

**Proof.** We can deduce from Theorem 2.2 the existence of  $x_0 \in H \setminus \{0\}$  such that

$$\operatorname{Re}\langle T_1^{n_1} \dots T_N^{n_N} x_0, x_0 \rangle > 0 \tag{4}$$

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for all  $n_j \ge 1$ ,  $j \in \{1, ..., N\}$ . Let us denote by  $\mathscr{P}_N$  the set of polynomials p in N variables, such that the summands of p have the form

$$cx_1^{n_1}\ldots x_N^{n_N}$$

with  $n_j \ge 1$  for all  $j \in \{1, ..., N\}$  and c > 0. Let us consider the cone

$$C = \{p(T_1,\ldots,T_N)(x_0) : p \in \mathscr{P}_N\}.$$

It is clear that C is invariant under each  $T_j$ ,  $j \in \{1, ..., N\}$  and by (4) C is non-trivial.

**Corollary 2.4.** Let  $T = (T_1, ..., T_N)$  be a N-tuple of commuting contractions, and let us suppose that  $(1, ..., 1) \in \sigma_{He}(T) \cap \mathbb{T}^N$  and  $T_j \in C_{\cdot 0}$  for each  $j \in \{1, ..., N\}$ . Then there exists a non-trivial closed cone C such that  $T_j(C) \subset C$  for each  $j \in \{1, ..., N\}$ .

**Proof.** Since  $T_i \in C_{.0}$ , then by Theorem 2.2

$$\operatorname{Re}\langle (T_1^*)^{n_1} \dots (T_N^*)^{n_N} x_0, x_0 \rangle \geq \alpha_{j(n)} \Leftrightarrow \operatorname{Re}\langle x_0, T_1^{n_1} \dots T_N^{n_N} x_0 \rangle \geq \alpha_{j(n)}.$$

Therefore

 $C = \{p(T_1, \ldots, T_N)(x_0) : p \in \mathscr{P}_N\}$ 

is a common invariant closed cone.  $\Box$ 

### 3. Concluding remarks and open problems

Let  $T = (T_1, T_2)$  a 2-tuple of contractions. If we change the hypothesis  $(1, 1) \in \sigma_{He}(T) \cap \mathbb{T}^2$ by  $(\mu_1, \mu_2) \in \sigma_{He}(T) \cap \mathbb{T}^2$  we can only get to

 $T_j(C) \subset \mu_j C, \quad j \in \{1, 2\}.$ 

It would be interesting if in this case we can find a common non-trivial invariant closed cone.

If  $T_1 \in C_0$  and  $T_2 \in C_0$ , with  $(1, 1) \in \sigma_{He}(T_1, T_2)$  the existence of a common invariant closed cone is not known.

Let us consider the subspaces

$$M_1 = \{x \in H \text{ such that } T_1^n T_2^n x \to 0\}$$
  

$$M_2 = \{x \in H \text{ such that } (T_1^*)^n (T_2^*)^n x \to 0\}.$$

 $M_1$  and  $M_2$  are invariant closed subspaces for  $T_j$  and  $T_j^*$ ;  $j \in \{1, 2\}$ , respectively, therefore,  $M_2^{\perp}$  is invariant by  $T_1, T_2$ . Hence, we can suppose that  $M_1$  and  $M_2$  are trivial, that is  $\{\theta\}$  or H.

Let us suppose that  $M_1 = H = M_2$ , then we said that  $T = (T_1, T_2)$  is of class  $K_{11}$  and in this case there exists a common non-trivial invariant subspaces for  $T_1$ ,  $T_2$  (see [2]).

If  $M_1 = \{0\}$  we say that T belongs to the class  $K_{0.}$ , and if  $M_2 = \{0\}$  T belongs to the class and  $K_{.0}$ . These cases are non-trivial. It would be interesting to investigate if Theorem 2.2 is true if  $T \in K_0$  or  $K_{.0}$ .

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